

Proposal for EPICS Interface for IU HV Control System

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CAEN HV GUI Example

File Edit CSS Window Help

OPI Runtime

caenA1525card.opi

CAEN SY1527 HV CHANNEL CONTROL

Channels 0-11 Channels 12-23

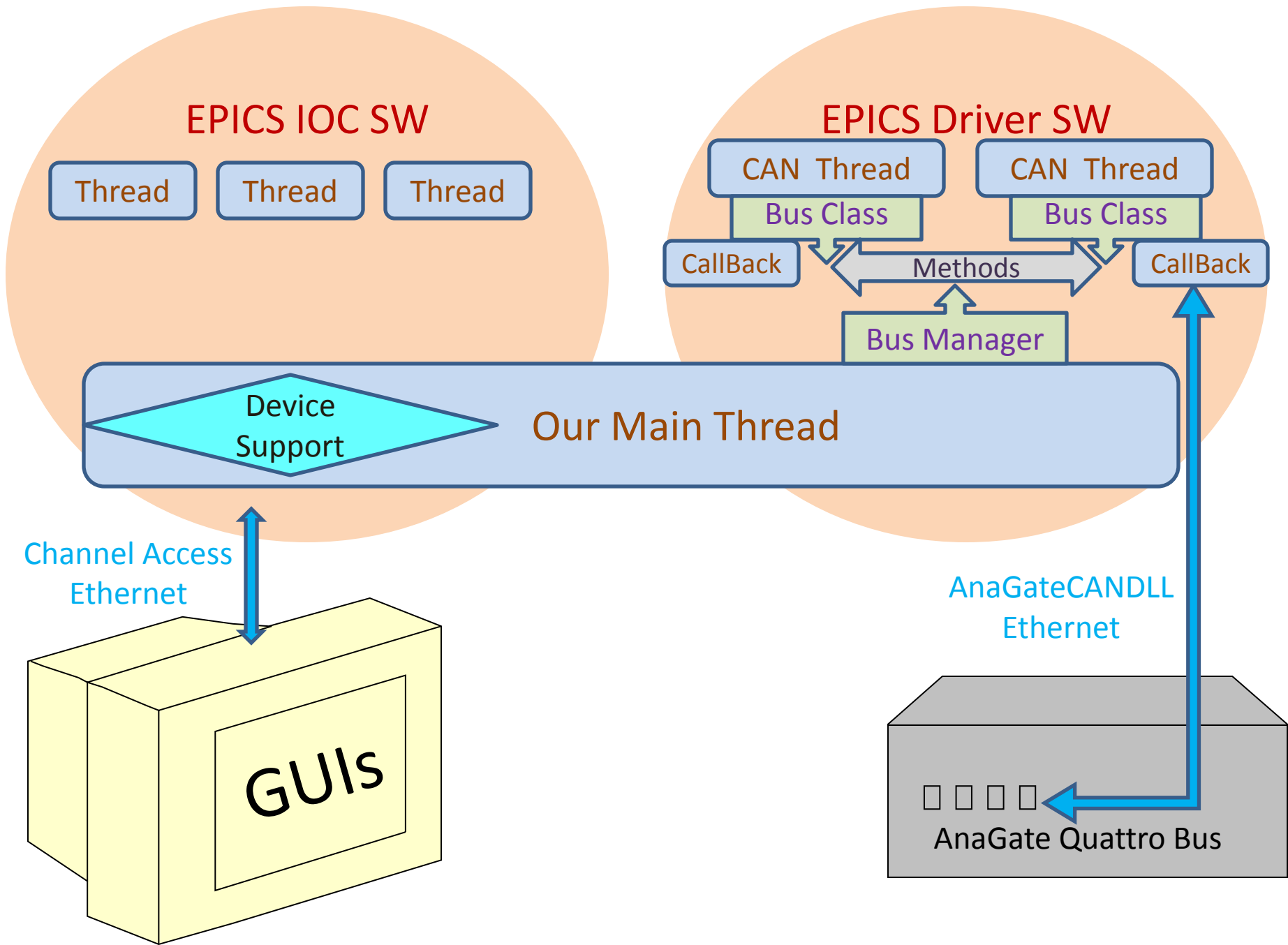
| Channel Name | Measured Voltage | Setpoint Voltage | HV ON/OFF | Channel Status | Measured Current | Trip Current | Trip Timeout | Software Max Voltage | Ramp up Rate | Ramp down Rate |
|--------------|------------------|------------------|-------------------------------------|----------------|------------------|--------------|--------------|----------------------|--------------|----------------|
| CHANNEL00 | 369.0 V | 1,982 | <input checked="" type="checkbox"/> | Ramping Up | 0.00 uA | 300.0 uA | 10.0 s | 3500.0 V | 20.0 V/s | 20.0 V/s |
| CHANNEL01 | 1236.0 V | 2,000 | <input type="checkbox"/> | Ramping Down | 0.00 uA | 300.0 uA | 10.0 s | 3500.0 V | 20.0 V/s | 20.0 V/s |
| CHANNEL02 | 0.0 V | 2,000 | <input type="checkbox"/> | Off | 0.00 uA | 300.0 uA | 10.0 s | 3500.0 V | 50.0 V/s | 50.0 V/s |
| CHANNEL03 | 0.0 V | 200 | <input type="checkbox"/> | Off | 0.00 uA | 300.0 uA | 10.0 s | 3500.0 V | 20.0 V/s | 20.0 V/s |
| CHANNEL04 | 0.5 V | 500 | <input type="checkbox"/> | Off | 0.00 uA | 300.0 uA | 10.0 s | 3500.0 V | 50.0 V/s | 50.0 V/s |
| CHANNEL05 | 199.5 V | 200 | <input checked="" type="checkbox"/> | On | 0.00 uA | 300.0 uA | 10.0 s | 3500.0 V | 50.0 V/s | 50.0 V/s |
| CHANNEL06 | 0.0 V | 200 | <input type="checkbox"/> | Off | 0.00 uA | 300.0 uA | 10.0 s | 3500.0 V | 50.0 V/s | 50.0 V/s |
| CHANNEL07 | 0.5 V | 500 | <input type="checkbox"/> | Off | 0.00 uA | 300.0 uA | 10.0 s | 3500.0 V | 30.0 V/s | 30.0 V/s |
| CHANNEL08 | 0.0 V | 200 | <input type="checkbox"/> | Off | 0.00 uA | 300.0 uA | 10.0 s | 3500.0 V | 50.0 V/s | 50.0 V/s |
| CHANNEL09 | 198.0 V | 200 | <input checked="" type="checkbox"/> | On | 0.00 uA | 300.0 uA | 10.0 s | 3500.0 V | 50.0 V/s | 50.0 V/s |
| CHANNEL10 | 0.0 V | 200 | <input type="checkbox"/> | Off | 0.00 uA | 300.0 uA | 10.0 s | 3500.0 V | 50.0 V/s | 50.0 V/s |
| CHANNEL11 | 0.0 V | 200 | <input type="checkbox"/> | Off | 0.00 uA | 300.0 uA | 10.0 s | 3500.0 V | 50.0 V/s | 50.0 V/s |

Suggested Principle

- Continuously scan the bus to maintain a synchronized buffer layer. Scan speed will depend on the bandwidth of the system.
- The requests to change hardware could be delayed, or they could be directly sent when modified by a “user”.
- Parameters values that EPICS records see may be “old” if requests come within a scan period.

EPICS Support Structure

- Our EPICS support would consist of three pieces:
 - Driver - Synchronizing software/hardware parameters
 - Device Support - Connecting values to EPICS PVs
 - EPICS application - Variables, GUIs, Alarms etc
- Driver part can be made independent of EPICS framework
- Device Support requests values from the buffer layer and assigns them to PVs.
- EPICS application is a set of EPICS records, GUIs, Alarm handlers etc, and can be dealt with together with CAEN HV system.



Bus and Callback Threads

Bus thread periodically requests all IDs on the bus to know which boards are alive.

For each HV parameter on the board:

- *Bus* thread periodically:
 1. Requests the parameter value from the “live” boards on the *bus* using the corresponding to that parameter *command*.
 2. Scans through all [*bus,board,command*] triplet FIFOs for that *bus* and *command*, and synchronizes the buffer layer until responses from all boards are received and processed. On TIMEOUT generate an error or raise an alarm.
 3. Write to boards if the parameter value on the board needs an (or can skip this and write every time an EPICS record is processed/modified by “user”).
- Callback thread:
 - Keeps reading the messages from the bus and fills up the FIFOs for each [*bus,board,command*] triplet.

Questions

- How is the trip current setting control implemented?
- Is there a ramp rate control in the firmware?
- What is the alarm logic for HVs? What is the DAC Voltage to ADC Voltage correspondence?
- What needs to be done with the LED control?
- How easy is it to add more parameters, like status indication: On, Off, Tripped, Ramping up etc to the board .
- Can a message from the board FULLY describe what command it is responding to using “extra bytes”?
- Does the board abandon a planned response if a new request is sent to it?